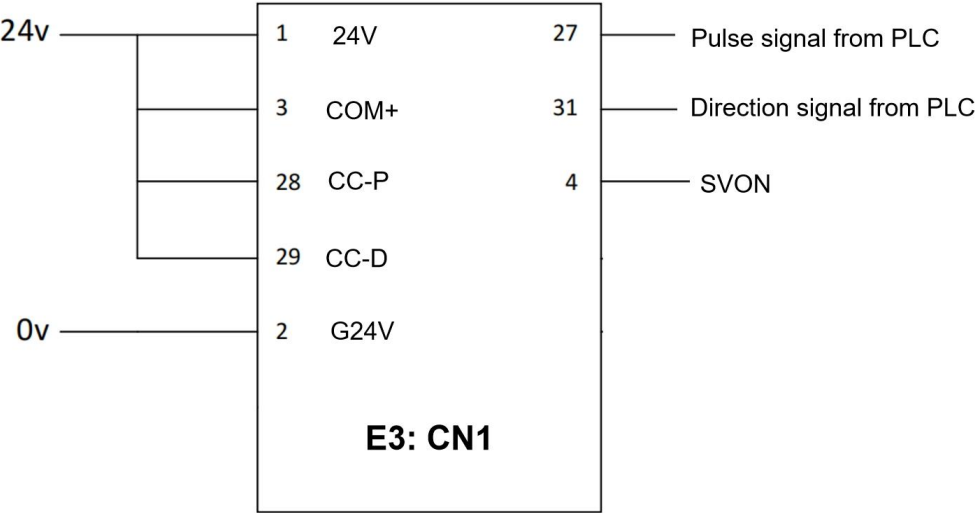


1. Please reset all parameters in order to no parameters be set wrongly.
 2. Set and make sure parameters as below:
 - 2.0r=0; Position control mode
 - 3.0r=1; Pulse command (Used in position control)
 - 32.0r=0; Pulse and direction: using pulse and direction input
 - 34.0r=32768 and 36.0r=2500 with this, PLC send 10000pulse, motor runs one turn.
- Note: After modifying any parameter, you must restart the drive to take effect.**
3. Wires as below, and please refer to attached catalog for CN1 layout details.



Description of User I/O connector (CN1) terminal arrangements

26	28	30	32	34	36	38	40	42	44	46	48	50
CMD_PLS	CC-P	CMD_DIR	A SPEED	A_TRQ	OUT_A	OUT_B	OUT_Z	SG	/485	G24	SP4	EDM-
27	29	31	33	35	37	39	41	43	45	47	49	
/CMD_PLS	CC-D	/CMD_DIR	A_GND	A_GND	OUT_A	OUT_B	OUT_Z	485	SG	SP3	EDM+	
1	3	5	7	9	11	13	15	17	19	21	23	25
VCC	COM1	I2(RESET)	I4(PCLR)	I6(CCWL)	I8(TLSEL1)	O1(MBRK)	O3(POSIN)	O5	O7+(SRDY+)	O8+(ALM+)	VCC	SP2
2	4	6	8	10	12	14	16	18	20	22	24	
G24	I1(SVON)	I3(HOLD)	I5	I7(CWL)	COM2	O2(SERVO)	O4	O6(OCZ)	O7-(SRDY-)	O8-(ALM-)		

Connector

